





# Recovery Rate of Clustering Algorithms

Fajie Li and Reinhard Klette

## Outline and Objective

#### **Abstract**

We provide a simple and general way for defining the recovery rate of clustering algorithms using a given family of old clusters for evaluating the performance when calculating a family of new clusters. The recovery rate may be calculated by using an approximate and efficient algorithm.

### Our Approach

Our general (!) evaluation of clustering algorithms is very intuitive. Our method does not need to introduce other functions such as, for example, an F-function as in [Larsen/Aone 1999], or entropy as in [Borgelt 2006] or [Crabtree et al. 2005].

## Recovery Rate and Exact Calculation

#### Clustering Algorithm

A clustering algorithm A maps a finite set

$$\cup_{k=1}^m G_k = C$$

 $C = \bigcup_{i=1}^{n} C_i$ , with  $N = \operatorname{card} C$  of old clusters) into a family of (new) clusters:

## Algorithm 1: Exact Recovery Rate

Input: Old clusters  $C_i$ , where i = 1, 2, ..., n; and new clusters  $G_j$ , where j = 1, 2, ..., m, obtained from a clustering algorithm  $\mathcal{A}$ .

Output: The recovery rate of A with respect to  $C_i$ , where i = 1, 2, ..., n.

- 1. Let M be an  $m \times n$  matrix, initially with zeros in all of its elements.
- 2. For each  $j \in \{1, 2, ..., m\}$  and for each  $x \in G_j$ , if there exists an  $i \in \{1, 2, ..., n\}$  such that  $x \in C_i$ , then update M as follows: M(j, i) = M(j, i) + 1, where M(j, i) is the (j, i)-th entry of M.
  - 3. Find m different integers (i.e., column indices)  $i_k \in \{1, 2, \ldots, n\}$  such that

$$\sum_{k=1}^{m} \frac{M(k, i_k)}{cardC_{i_k}} = \max\{\sum_{j=1}^{m} \frac{M(j, i_j)}{cardC_{i_j}} : i_j \in \{1, 2, \dots, n\}\}$$

4. Output the recovery rate as being the value

$$\frac{\sum_{k=1}^{m} \frac{M(k, i_k)}{cardC_{i_k}}}{m} \times 100\%$$

## Definition of Recovery Rate

**Definition 2.** Assume that  $G_{1_{t'_1}}$ ,  $G_{2_{t'_2}}$ , ...,  $G_{m_{t'_m}}$  satisfy

(i) For  $i, j \in \{1_{t'_1}, 2_{t'_2}, \dots, m_{t'_m}\}$ , there exist two old clusters  $C_i$  and  $C_j$  such that  $G_{i_{t'_i}} \subseteq C_i$  and  $G_{j_{t'_i}} \subseteq C_j$ ; and

(ii) 
$$\sum_{k=1}^{m} \frac{^{cardG_{k_{t'_{k}}}}}{^{cardG_{k}}} = \max\{\sum_{k=1}^{m} \frac{^{cardG_{k_{t_{k}}}}}{^{cardG_{k}}}: t_{k} = 1, 2, \dots, s_{k}\}$$

 $The\ value$ 

$$\frac{\sum_{k=1}^{m} \frac{cardG_{k_{t'_{k}}}}{cardC_{k}}}{m} \times 100\%$$

is called the recovery rate of the clustering algorithm  $\mathcal{A}$  with respect to the input  $\bigcup_{i=1}^{n} C_i$ .

# Time-Efficient Approximate Calculation

This exact algorithm requires exponential run-time. The following is only an approximate algorithm for computing the recovery rate, but with O(mn) run-time. Below we also provide an example (from astronomy: synthesized galaxies) for applying these two algorithms. There are five old clusters with 10,000 3D points each. The figure shows a 2D projection of the union of all five old clusters. We apply an adaptive mean-shift clustering algorithm (see Georgescu et al. 2003), but further optimized (see Li/Klette, ICONIP 2008). The recovery rate equals 58.18%, and the approximate algorithm estimates this rate as 51.76%.

#### Algorithm 2: Approximate Recovery Rate

Input and Steps 1 and 2 are the same as in Algorithm 1.

Output: The approximate recovery rate of  $\mathcal{A}$  with respect to  $C_i$ , where i = 1, 2, ..., n.

3.0. For each entry 
$$M(i,j)$$
 of  $M$ , let  $M(i,j) = \frac{M(i,j)}{cardC_j}$ , where  $i=1,\,2,\,\ldots,\,m;\,j=1,\,2,\,\ldots,\,n.$ 

3.1. For each 
$$j \in \{1, 2, ..., m\}$$
, find the maximum entry of  $M$ , denoted by  $m_j = M(i, k)$ .

$$3.2.$$
 Update  $M$  by removing the  $i$ -th row and  $k$ -th column of  $M$  and go to Step  $3.1.$ 

4. Output the approximate recovery rate as the value

$$\frac{\sum_{j=1}^{m} m_j}{m} \times 100\%$$

Clustering is often used in image and video processing, and the specified technique allows to compare the performance of various clustering algorithms (for image segmentation, learning, bags-of-features representations of images, video retrieval etc.).