



<http://researchspace.auckland.ac.nz>

ResearchSpace@Auckland

Copyright Statement

The digital copy of this thesis is protected by the Copyright Act 1994 (New Zealand).

This thesis may be consulted by you, provided you comply with the provisions of the Act and the following conditions of use:

- Any use you make of these documents or images must be for research or private study purposes only, and you may not make them available to any other person.
- Authors control the copyright of their thesis. You will recognise the author's right to be identified as the author of this thesis, and due acknowledgement will be made to the author where appropriate.
- You will obtain the author's permission before publishing any material from their thesis.

To request permissions please use the Feedback form on our webpage.

<http://researchspace.auckland.ac.nz/feedback>

General copyright and disclaimer

In addition to the above conditions, authors give their consent for the digital copy of their work to be used subject to the conditions specified on the Library Thesis Consent Form.

**Water Wave Scattering
by
Floating Elastic Plates
with
Application to Sea-Ice**

This thesis is for examination purposes only and may not be consulted or referred to by any persons other than the examiner.

Alison L. Kohout

November 2008

Supervised by

Dr. Michael H. Meylan

A THESIS SUBMITTED FOR THE DEGREE OF
DOCTOR OF PHILOSOPHY IN MATHEMATICS
AT THE UNIVERSITY OF AUCKLAND, NEW ZEALAND

Abstract

This thesis considers the scattering of small amplitude water waves, obliquely incident on a set of floating elastic plates occupying the entire water surface. The problem is two-dimensional and assumes invariance in the width of the plates. All non-linear physical effects are neglected. The plates are floating on a body of water of finite depth and each plate has uniquely defined properties. The problem is formulated by imposing boundary conditions on the eigenfunction expansion of Laplace's equation. A set of transmission and reflection coefficients is generated, which is solved by applying the edge conditions and matching at each plate boundary. We label this solution method the Matched Eigenfunction Expansion Method (MEEM). The problem is solved for a variety of edge conditions including free, clamped, sliding, springed and hinged. To verify the MEEM results, the problem is also solved using a Green Function Method. The convergence of the two methods is compared and found to be almost identical. The MEEM is used to simulate wave-ice interaction in the Marginal Ice Zone (MIZ). The model removes the resonance effects and predicts that the transmitted energy is independent of floe length, provided the wavelength is more than three times the floe length. The model predicts an exponential decay of wave energy with distance of propagation through the MIZ, which agrees with experimental findings. The results have been summarised in a graph with the attenuation coefficient expressed as a function of period for various floe thicknesses. We also provide an estimate of the attenuation coefficient using an approximation theory. The displacements of the MEEM are compared against a series of laboratory experiments performed in a two-dimensional wave-tank and show good agreement. The attenuation model results are compared against a series of field experiments carried out in the Arctic and off the West Antarctic Peninsula. Generally, the decay rates of the model agree well with the field experiments in diffuse ice. We suggest that factors other than wave scatter are relevant in models of wave-attenuation in non-diffuse ice.

Acknowledgements

Many people have helped make this thesis possible. Firstly, and most importantly, I would like to thank my supervisor, Mike Meylan. Mike has proved to be a fantastic mentor whose expertise and encouragement have played a vital role in making this thesis run smoothly and enjoyably. Mike has been a committed supervisor, who throughout the last three years has put in a considerable amount of effort and has been very generous with his time.

A vital section of this thesis has relied on experimental and field data. I would like to thank Shigeki Sakai and his team for their work on the wave-tank experimental data. I would also like to thank Will Perrie and Daniel Hayes for providing us with their field data.

The development of the code used in this thesis was assisted by Pierre Leman, Damien Brossard and Tim Williams. I would further like to thank the Otago team including Vernon Squire, Tim Williams, Gareth Vaughan and Pat Langehorne for their time and valuable advice throughout this thesis. Towards the end of the thesis, Malte also proved to be invaluable in providing advice and I greatly appreciate his efforts in the arduous task of proof reading my thesis. I would also like to acknowledge Garry Tee for his valuable assistance proof reading our papers.

Throughout my PhD, I have been heavily reliant on my PhD Scholarship, which was funded by Marsden Grant U00308 from the New Zealand government. This has covered my PhD fees and living expenses. I have also been fortunate during my PhD and have had the opportunity to travel to both local and international conferences and workshops. This has been possible thanks to the financial support from the Auckland University Department of Mathematics, the Auckland University Research Fund, the New Zealand Study Abroad Award and Svalbard University.

Last, but certainly not least, I would like to thank my family and my partner Chris for their invaluable support in many ways throughout this PhD.

Contents

List of Figures	xii
List of Tables	xiii
Nomenclature	xv
1 Introduction	1
2 Background	5
2.1 Sea-Ice and the Marginal Ice Zone (MIZ)	5
2.2 Wave-Ice Modelling	6
2.2.1 Early Findings	7
2.2.2 Scattering Models	7
2.2.3 Viscous Models	10
2.3 Wave Attenuation	10
2.3.1 Wave Attenuation Models	11
2.3.2 Wave Attenuation Field Experiments	11
2.4 Strain and Floe Break-up	14
2.5 Very Large Floating Structures (VLFS)	15
3 Formulation and Preliminaries	17
3.1 Introduction	17
3.2 The Problem	17
3.3 Assumptions and Conditions	18
3.3.1 The Seabed	18
3.3.2 The Free Surface	19
3.3.3 The Covered Surface	19
3.3.4 The Plate Edges	20
3.4 Non-Dimensionalising the Variables	22

3.5	Final Equations	22
4	The Matched Eigenfunction Expansion Method	25
4.1	Introduction	25
4.2	Method of Solution	25
4.2.1	Eigenfunction Expansion	25
4.2.2	The Velocity Potential	28
4.2.3	The Displacement	29
4.2.4	Eigenfunction Matching	29
4.3	Wave Propagation Through Two Semi-Infinite Elastic Plates	30
4.4	Wave Propagation Through a Set of Plates	34
4.4.1	Arbitrary Depth	34
4.4.2	Shallow Water	41
4.4.3	The Free Surface Formulation	45
5	The Green Function Method	47
6	Articulated Plates	55
6.1	Introduction	55
6.2	Matched Eigenfunction Expansion Method	56
6.2.1	Simple Connections	56
6.2.2	Springed Connections	58
6.2.3	Hinged Connections	62
6.3	The Green Function Method	63
6.3.1	Simple Connections	63
6.3.2	Springed Connections	65
6.3.3	Hinged Connections	69
7	Accuracy and Efficiency of Solutions	71
7.1	Introduction	71
7.2	Energy Balance	71
7.3	Verifying the Matched Eigenfunction Expansion Methods Reflection and Transmission Coefficients	72
7.4	Solution Convergence	77
8	Modelling an Idealised Marginal Ice Zone	79
8.1	Introduction	79
8.2	Setting the Variables	80

8.3	Floe Length	81
8.4	Period and Floe Thickness	88
8.5	Number of Floes	90
8.6	Attenuation Coefficient	92
8.7	Strain	93
8.7.1	Modelling Strain	93
8.7.2	The strain for a Wave Spectrum	97
9	Approximation Theory	103
9.1	Introduction	103
9.2	Approximation Theory	103
9.3	Wave Attenuation Approximation	107
10	Comparing Theory to Experiments	111
10.1	Introduction	111
10.2	Wave Tank Experiment	112
10.3	Field Experiments	120
10.3.1	Greenland Sea 1979	120
10.3.2	Bering Sea 1979	124
10.3.3	Greenland Sea 1983	125
10.3.4	Bering Sea 1983	128
10.3.5	Bellinghausen Sea 2003	131
10.3.6	Summary / Discussion	134
11	Summary and Conclusions	137
	Bibliography	149
	Appendix	149
A	The Energy Balance Equation	151
B	Deriving $T_{av} ^2$	159
C	The Attenuation Data	161

List of Figures

3.1	A schematic diagram of wave propagation through a set of floating plates. . .	18
4.1	A schematic diagram of the incident, reflected and transmitted waves . . .	26
4.2	A schematic diagram of wave propagation through two semi-infinite plates.	30
4.3	A schematic diagram of wave propagation through a set of plates.	34
5.1	A schematic diagram showing the area, \mathcal{U} bounded by the contour \mathcal{S}	48
7.1	The MEEM and GFM solutions for the reflected and transmitted coefficients for plates with free edges.	73
7.2	The MEEM and GFM solutions for the reflected and transmitted coefficients for plates with basic edge conditions.	74
7.3	The MEEM and GFM solutions for the reflected and transmitted coefficients for plates connected by springs.	75
7.4	The MEEM and the finite-floe's reflected and transmitted coefficients. . . .	76
8.1	The transmitted energy as a function of floe length.	81
8.2	The mean transmitted energy as a function of mean floe length for various periods.	83
8.3	The mean transmitted energy as a function of mean floe length for various floe thicknesses.	84
8.4	The mean transmitted energy as a function of mean floe length for a various number of plates.	85
8.5	Mean transmitted energy as a function of mean floe length calculated via various distributions.	86
8.6	The displacement as a function of distance.	87
8.7	The mean transmitted energy as a function of period for various floe thicknesses.	88

8.8	The mean transmitted energy as a function of mean floe thickness for various periods.	89
8.9	The logarithm of the mean transmitted energy as a function of the number of floes for various periods.	90
8.10	The logarithm of the mean transmitted energy as a function of the number of floes for various floe thicknesses.	91
8.11	Predictions of the logarithm of the attenuation coefficient as a function of period for various floe thicknesses.	92
8.12	A replica of a figure of the absolute strain produced in Fox and Squire (1991).	94
8.13	The absolute value of the strain as a function of distance for various periods.	95
8.14	Maximum strain as a function of period for various floe thicknesses.	96
8.15	The JONSWAP and Pierson–Moskowitz spectrums as a function of frequency.	98
8.16	The Pierson–Moskowitz spectrum as a function of period for various peak periods.	98
8.17	Amplitude as a function of period after Λ floes.	99
8.18	The spectral strain and spectral strain envelope as a function of distance.	100
8.19	The natural logarithm of the maximum strain envelope as a function of Λ	101
8.20	The significant wave height as a function of Λ	102
9.1	A schematic diagram showing the wave reflection and transmission through a long and wide finite plate.	105
9.2	A detailed schematic diagram showing the wave reflection and transmission through a long and wide finite plate.	106
9.3	The absolute value of the reflection coefficient as a function of floe length.	107
9.4	A comparison between the model and approximated attenuation coefficients.	109
10.1	Displacements from the MEEM compared against the wave-tank experiment for various incident amplitudes, with plates 5mm thick.	113
10.2	Displacements from the MEEM compared against the wave-tank experiment for various periods, with a plate 5mm thick.	114
10.3	Displacements from the MEEM compared against the wave-tank experiment for various amplitudes, with a plate 20 mm thick.	114
10.4	Displacements from the MEEM compared against the wave-tank experiment for various amplitudes, with two plates 20 mm thick.	115
10.5	Displacements from the MEEM compared against the wave-tank experiment for various amplitudes, with four plates 20 mm thick.	115

10.6	Displacements from the MEEM compared against the wave-tank experiment for various amplitudes, with eight plates 20 mm thick.	116
10.7	Displacements from the MEEM compared against the wave-tank experiment for various amplitudes, with sixteen plates 20 mm thick.	116
10.8	Displacements from the MEEM compared against the wave-tank experiment for various periods, with a single plate 20 mm thick.	117
10.9	Displacements from the MEEM compared against the wave-tank experiment for various periods, with two plates 20 mm thick.	117
10.10	Displacements from the MEEM compared against the wave-tank experiment for various periods, with four plates 20 mm thick.	118
10.11	Displacements from the MEEM compared against the wave-tank experiment for various periods, with eight plates 20 mm thick.	118
10.12	Displacements from the MEEM compared against the wave-tank experiment for various periods, with sixteen plates 20 mm thick.	119
10.13	Displacements from the MEEM compared against the wave-tank experiment for various periods, with thirty-two plates 20 mm thick.	119
10.14	Attenuation coefficients compared against the 4 th September 1979 Greenland Sea experiment for $\tau = 3.1$	122
10.15	Attenuation coefficients compared against the 4 th September 1979 Greenland Sea experiment for $\tau = 2$ and $\tau = 3.5$	123
10.16	Attenuation coefficients compared against the 10 th September 1979 Greenland Sea experiment.	123
10.17	Attenuation coefficients compared against the 1979 Bering Sea experiment.	125
10.18	Attenuation coefficients compared against the 26 th July 1983 Greenland Sea experiment.	127
10.19	Attenuation coefficients compared against the 29 th July 1983 Greenland Sea experiment.	127
10.20	Attenuation coefficients compared against the 7 th February 1983 Bering Sea experiments.	129
10.21	Attenuation coefficients compared against the 20 th , 22 nd and 26 th February 1983 Bering Sea experiments.	131
10.22	Attenuation coefficients compared against the Bellinghausen Sea experiment 323.	133
10.23	Attenuation coefficients compared against the Bellinghausen Sea experiment 324.	133
A.1	A diagram depicting the area \mathcal{U} which is bounded by the rectangle \mathcal{S}	151

List of Tables

7.1	Solutions of $ T $ from the MEEM and the GFM.	77
7.2	Solutions of $ T $ from the MEEM and Meylan and Squire (1994)'s finite-floe model.	77
C.1	The attenuation coefficients from the 4 th September 1979 Greenland Sea experiment.	161
C.2	The attenuation coefficients from the 10 th September 1979 Greenland Sea experiment.	162
C.3	The attenuation coefficients from the 7 th February 1983 the Bering Sea experiment 1.	162
C.4	The attenuation coefficients from the 7 th February 1983 the Bering Sea experiment 2.	163
C.5	The attenuation coefficients from the 20 th February 1983 the Bering Sea experiment.	163
C.6	The attenuation coefficients from the 22 nd February 1983 the Bering Sea experiment.	164
C.7	The attenuation coefficients from the 26 th February 1983 the Bering Sea experiment.	164
C.8	The attenuation coefficients from the 26 th July 1983 the Greenland Sea experiment.	165
C.9	The attenuation coefficients from the 29 th July 1983 the Greenland Sea experiment.	165
C.10	The attenuation coefficients from the 24 th March 2003 Bellinghausen Sea experiment 323.	166
C.11	The attenuation coefficients from the 25 th March 2003 Bellinghausen Sea experiment 324 on entering the ice.	166
C.12	The attenuation coefficients from the 25 nd March 2003 Bellinghausen Sea experiment 324 on exiting the ice.	167

Nomenclature

a	Attenuation coefficient	90
\check{a}	Attenuation coefficient from field Experiments	120
\tilde{a}	Approximated attenuation coefficient	108
A	Wave amplitude	99
α	Frequency squared	23
β	Stiffness constant	23
\mathcal{C}	Term appearing in the Green's Function	48
C	Concentration of ice	120
CI	Confidence Interval	121
D	Rigidity constant	20
\mathcal{D}	Energy balance coefficient	72
E	Transmitted energy	80
η	Displacement	18
η^s	Shallow water displacement	42
η^I	Incident displacement	50
$\eta^+(x'_n)$	Right edge of the n^{th} discontinuity	65
$\eta^-(x'_n)$	Left edge of the n^{th} discontinuity	65
f	Rayleigh's distribution	82
g	Gravitational constant	19
G	Free-Surface Green Function for a floating elastic plate	47
\mathcal{G}	Simplifying term in the Green Function	50
GFM	Green Function Method	1
γ	Mass constant	22
H_s	Significant wave height	102
ω	Frequency	18
h	Water depth	18
I	Incident wave amplitude in potential	28
\Im	The imaginary part of a complex number	72
k	Wave number in the z direction	26
κ	Wave number in the x direction	26
k_y	Wave number in the y direction	18
k^f	Free surface wave number in the z direction	27

l	Left edge of the plate	20
l'	Actual floe length	82
L	Length of the plate	81
\mathcal{L}	Scaling length parameter	22
Λ	Number of plates	28
M	Number of positive real roots of the dispersion equation	28
MEEM	Matched Eigenfunction Expansion Method	1
MIZ	Marginal Ice Zone	5
μ	Plate number	19
$\bar{\mu}$	Mean floe length	82
ν	Poisson's constant	20
ω	Frequency	18
ω_m	Peak frequency	97
p	Rayleigh distribution probability	82
P	Pressure at the water surface	19
Φ	Time dependant velocity potential	18
ϕ	Time independent velocity potential	18
ϕ^s	Shallow water velocity potential	41
r	Right edge of the plate	20
R	The reflected potential coefficient	28
\tilde{R}	An approximation of the reflected potential coefficient	103
R_{pw}	The reflected coefficient from a plate to open water	103
R_{wp}	The reflected coefficient from open water to a plate	104
\Re	The real part of a complex number	18
ρ	Density of the plate	19
ρ_w	Water density	19
S	Strain at the surface of an ice plate	93
S_T	Spectral strain	100
S_E	Strain envelope	100
\mathcal{S}	The contour of the modelled region	48
s_r	Rotational spring constant	21
s_v	Vertical spring constant	21
σ	Peak width	97
t	Time	18
T	Transmitted potential coefficient	28
\tilde{T}	An approximation of the transmitted coefficient	103
T_{pw}	The transmitted coefficient from a plate to open water	103
T_{wp}	The transmitted coefficient from open water to a plate	104
T_{av}	The average of the transmitted coefficient over one period	107
\mathcal{T}	Incident wave period	80
\mathcal{T}_m	Peak period	101
τ	Plate thickness	19
θ	Incident angle	27
\mathcal{U}	Area of the modelled region	48

Υ	Power Spectrum of waves	97
v	Peak enhancement factor	97
VLFS	Very Large Floating Structures	15
x	Horizontal co-ordinate of the problem	18
x'	Shifting variable in the Green function	48
x'_n	Position of the n^{th} discontinuity	49
y	Horizontal co-ordinate of the problem	18
Y	Effective Young's modulus	20
z	Vertical co-ordinate of the problem	18
$[F]$	Denotes the jump in the function F	50
F^*	Denotes the conjugate of F	104

