General Dynamic Dynamic Logic

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Advances in Modal Logic, Copenhagen, 2012

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Dynamic Dynamic?

Dynamic - as in Propositional Dynamic Logic (PDL)

Dynamic - as in Dynamic Epistemic Logic (DEL)

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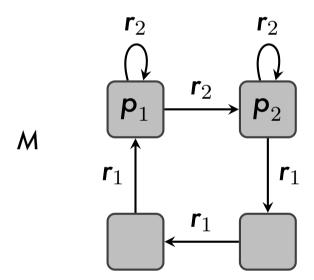
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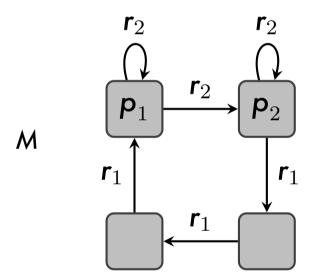
Defining Relations with PDL

Within this model, we can define new relations using PDL.



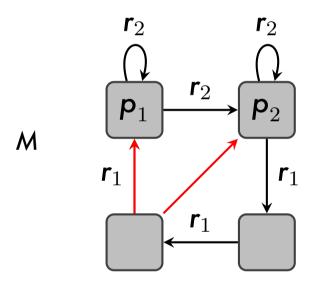
Defining Relations with PDL: Composition

Composition: r_1 ; r_2



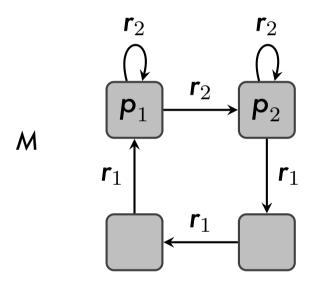
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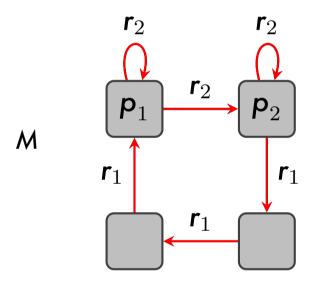
Defining Relations with PDL: Choice

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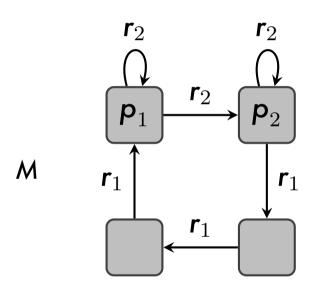
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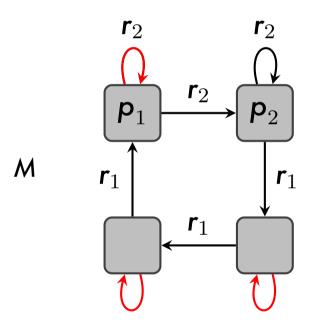
Defining Relations with PDL: Test

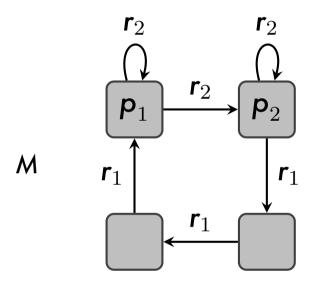
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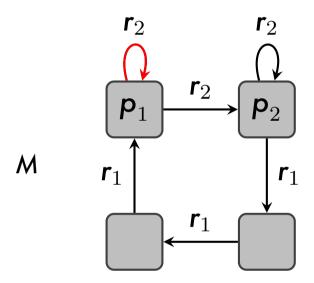


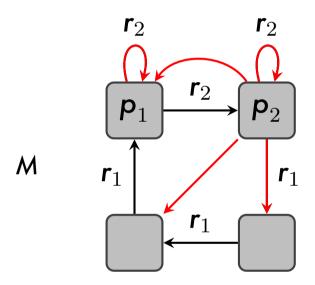
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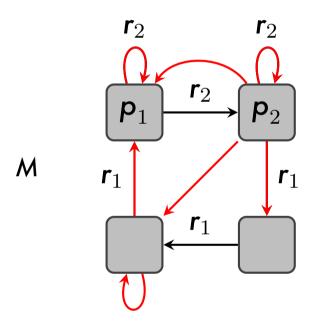
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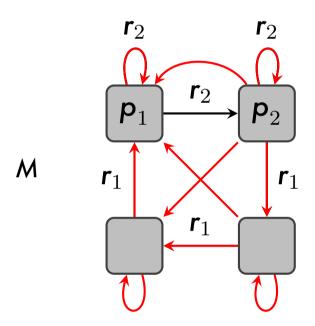






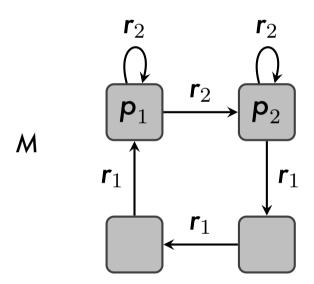






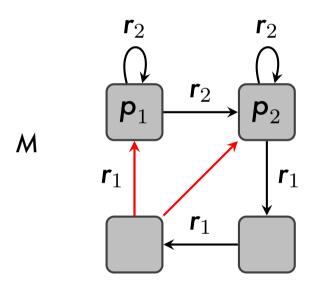
Defining Relations with PDL: Programs

Program: $(\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1?; \mathbf{r}_2)$



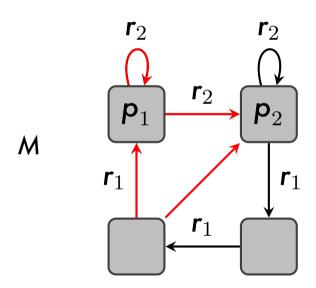
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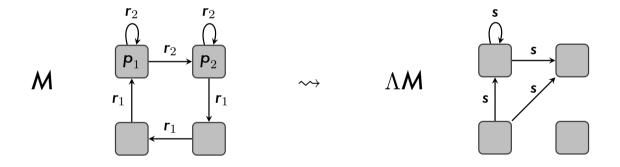
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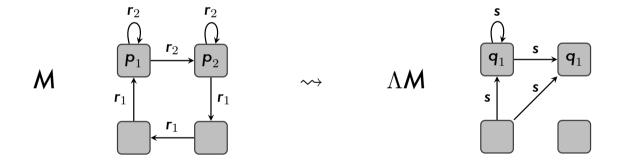


$$\Lambda(\mathbf{s}) = (\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1?; \mathbf{r}_2)$$

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$$\begin{array}{ll} \Lambda(\mathbf{q}_1) &= \langle \mathbf{r}_2 \rangle \neg \mathbf{p}_1 \\ \\ \Lambda(\mathbf{s}) &= (\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1?; \mathbf{r}_2) \end{array}$$



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PDL Transformations: Signatures

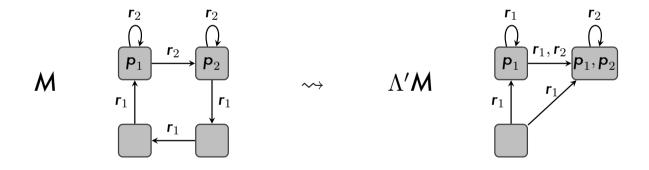
The Λ of our example changed the signature of the model.

$$\begin{array}{ll} \textit{M} & \text{has signature } \{ \textbf{p}_1, \textbf{p}_2, \textbf{r}_1, \textbf{r}_2 \} \\ \Lambda \textit{M} & \text{has signature } \{ \textbf{q}_1, \textbf{q}_2, \textbf{s} \} \end{array}$$

But we can also define signature-preserving transformations...

PDL Transformations: Signature preserving

$$\begin{array}{ll} |\Lambda'| &= \langle \mathbf{r}_1 \rangle \mathbf{p}_1 \vee \langle \mathbf{r}_2 \rangle \mathbf{p}_2 \\ \Lambda'(\mathbf{p}_1) &= \langle \mathbf{r}_2 \rangle \neg \mathbf{p}_1 \\ \Lambda'(\mathbf{p}_2) &= \langle \mathbf{p}_2 ?; \mathbf{r}_1 \rangle \neg \mathbf{p}_2 \\ \Lambda'(\mathbf{r}_1) &= (\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1 ?; \mathbf{r}_2) \\ \Lambda'(\mathbf{r}_2) &= \mathbf{r}_2 \end{array}$$



PDL Dynamic Operators

For $\mathbf{u} \in |\Lambda|$,

$$\mathbf{M}, \mathbf{u} \models [\Lambda] \varphi \quad \text{iff} \quad \Lambda \mathbf{M}, \mathbf{u} \models \varphi$$

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Note that φ is in the signature of ΛM .

PDL Dynamic Operators: Translation

Given Λ and φ (in sig Λ **M**), find φ^{Λ} (in sig **M**) such that

$$M, \mathbf{u} \models \varphi^{\Lambda} \quad \text{iff} \quad \Lambda M, \mathbf{u} \models \varphi$$

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PDL Dynamic Operators: Translation Example

We want to calculate φ^{Λ} from φ .

$$\begin{array}{ll} |\Lambda| &= \langle \mathbf{r}_1 \rangle \mathbf{p}_1 \vee \langle \mathbf{r}_2 \rangle \mathbf{p}_2 \\ \Lambda(\mathbf{q}_1) &= \langle \mathbf{r}_2 \rangle \neg \mathbf{p}_1 \\ \Lambda(\mathbf{q}_2) &= \langle \mathbf{p}_2 ?; \mathbf{r}_1 \rangle \neg \mathbf{p}_2 \\ \Lambda(\mathbf{s}) &= (\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1 ?; \mathbf{r}_2) \end{array}$$

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$$\langle \mathbf{s}; \mathbf{s} \rangle \mathbf{q}_1 \quad \mapsto \quad \langle \Lambda(\mathbf{s}); |\Lambda|?; \Lambda(\mathbf{s}); |\Lambda|? \rangle \Lambda(\mathbf{q}_1)$$

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Expands to:

$$\langle (\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1?; \mathbf{r}_2); \langle \mathbf{r}_1 \rangle \mathbf{p}_1 \vee \langle \mathbf{r}_2 \rangle \mathbf{p}_2?; (\mathbf{r}_1; \mathbf{r}_2) \cup (\mathbf{p}_1?; \mathbf{r}_2); \langle \mathbf{r}_1 \rangle \mathbf{p}_1 \vee \langle \mathbf{r}_2 \rangle \mathbf{p}_2? \rangle \langle \mathbf{r}_2 \rangle \neg \mathbf{p}_1 \rangle \langle \mathbf{r}_1 \rangle \langle \mathbf{r}_2 \rangle \langle \mathbf{$$

PDL Dynamic Operators: Axiomatisation

Extend the standard axioms and rules of PDL with the schema:

$$[\Lambda]\varphi \leftrightarrow \varphi^{\Lambda}$$

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Extend the standard axioms and rules of PDL with the schema:

$$[\Lambda]\varphi \leftrightarrow \varphi^{\Lambda}$$

This is complete and decidable.

Decidable Extensions of PDL

- relational converse r°
- the universal relation **E**
- relational complement -r
- intersection $r_1 \cap r_2$

Walther, D. (2004) Propositional Dynamic Logic with Negation on Atomic Programs, Msc Thesis, Dresden University of Technology.

Lutz, C. (2005). PDL with Intersection and Converse Is Decidable. In L. Ong (Ed.), Computer Science Logic, Springer LNCS 3634, pp. 413–427.

PDL Dynamic Operators: Applications

Announcement of φ :

 $\begin{array}{ll} |\Lambda| &= \varphi \\ \Lambda(\leq) &= (\varphi?; \leq; \varphi?) \cup (\neg \varphi?; \leq; \neg \varphi?) \\ & \vdots & \vdots & \vdots \\ \end{array}$ Upgrade with belief that φ :

 $\cup (\neg \varphi?; \textbf{\textit{E}}; \varphi?)$ Upgrade with preference for φ : $\Lambda(\preceq) = (\preceq \cup (\neg \varphi?; \textbf{\textit{E}}; \varphi?))^*$

- \leq is a plausibility ordering;
- \preceq is a preference ordering and \top is the universal relation.

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C.f.

Plaza, J., Logics of public communications, Synthese 158 (2007), pp. 165-179.

van Benthem, J. 'Dynamic logic for belief revision', Journal of Applied Non-classical Logic 17, (2007), pp. 129-155.

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PDL Dynamic Operators: Example from Epistemic Doxastic Logic

 \leq_1 and \leq_2 are preorders (plausibility for agents 1 and 2); \sim_1 and \sim_2 are equivalences (indistinguishability for agents 1 and 2). Agent i knows that φ in state \mathbf{w} iff φ holds in every $\mathbf{v} \sim_i \mathbf{w}$.

Agent i believes that φ in state \mathbf{w} iff φ holds in every \leq_i -maximal state $\mathbf{v} \sim_i \mathbf{w}$.

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$$\uparrow_1 \mathbf{r}(\leq_1) = (\mathbf{r}?; \leq_1; \mathbf{r}?) \cup (\neg \mathbf{r}?; \leq_1; \neg \mathbf{r}?) \cup (\neg \mathbf{r}?; \sim_1; \mathbf{r}?)$$

 $([\uparrow_1 r]M)$ is the result of agent 1 upgrading with a belief that r.)

PDL Dynamic Operators: Example from Epistemic Doxastic Logic

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Agent i knows that φ in state w iff φ holds in every $v \sim_i w$. Agent i believes that φ in state w iff φ holds in every \leq_i -maximal state $v \sim_i w$.

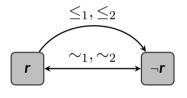
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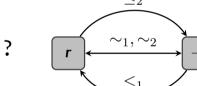
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$$M$$
 r
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Private Belief Change: The Problem

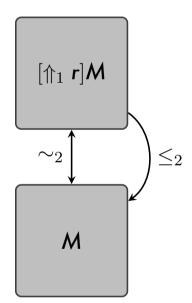
If the change to agent 1's beliefs is *private* then agent 2 should not know whether she is in M or in $[\uparrow_1 r]M$.





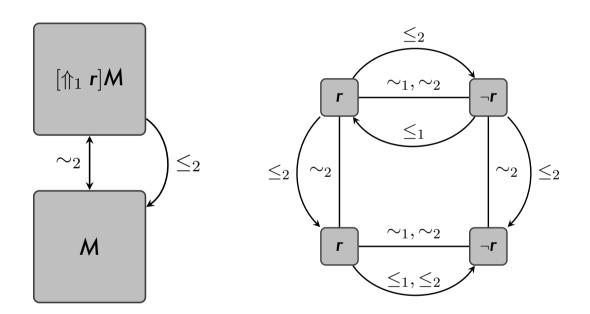
Private Belief Change: The Solution

If the change to agent 1's beliefs is *private* then represent agent 2's ignorance within the model:



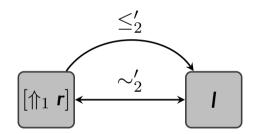
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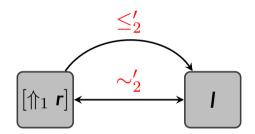
General Dynamic Operators: The Core Idea

Represent dynamic operators as (finite) models:



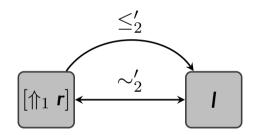
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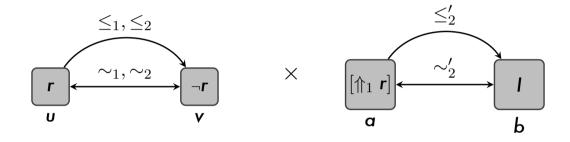
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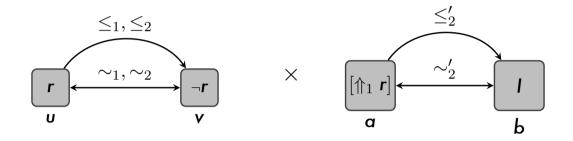


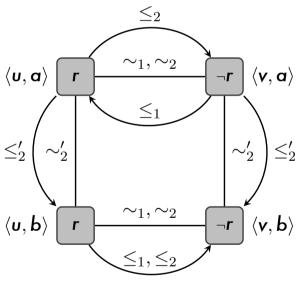
C.f. [BMS] Baltag, A., L. S. Moss and S. Solecki, The logic of public announcements, common knowledge and private suspicious, Technical Report SEN-R9922, CWI, Amsterdam (1999)

General Dynamic Operators: Computing the Product

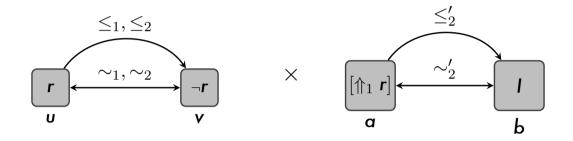


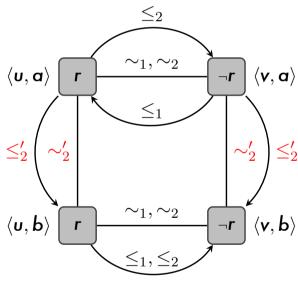
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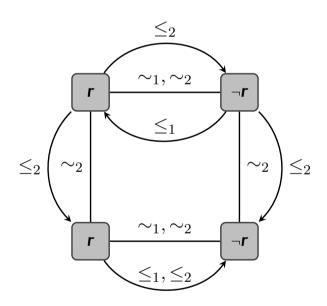




General Dynamic Operators: Integrating

Use PDL again to compute the final model:

$$\sim_i := (\sim_i; \sim_i')^*$$
 and $\leq_i := (\leq_i; \leq_i')^*$



General Dynamic Operators: Applications

- BMS, the original system of dynamic epistemic logic with private change
- LCC, the 'logic of communication and change'
- Priority Update: variant of BMS to cope with belief revision
- Facebook Logic: reasoning about changes to social networks

C.f. [LCC] van Benthem, J., van Eijck, J. and Kooi, B. (2006), Logics of communication and change, Information and computation 204, pp. 1620–1662.

[Priority Update] Baltag, A., and Smets, S. (2008). A qualitative theory of dynamic interactive Belief Revision. In Bonanno, G., van der Hoek, W., and Wooldridge, M. (Eds.), Logic and the Foundations of Game and Decision Theory, Texts in Logic and Games (Vol. 3). Amsterdam University Press.

General Dynamic Operators: GDDL

A GDDL dynamic operator $[A, G, H, \alpha]$ on models of signature $\langle P, R \rangle$ consists of four things:

- a finite model $\mathbf{A} = \langle \mathbf{D}, \mathbf{U} \rangle$ of some finite signature $\langle \mathbf{Q}, \mathbf{S} \rangle$,
- ② a PDL-transformation G_d from $\langle P, R \rangle$ to $\langle P, R \rangle$ for each $d \in D$,
- **3** a PDL-transformation H from $\langle P \cup Q, R \cup S \rangle$ to $\langle P, R \rangle$, and
- **1** a distinguished element $a \in D$.

 $(\langle \mathbf{Q}, \mathbf{S} \rangle)$ must be distinct from $\langle \mathbf{P}, \mathbf{R} \rangle$.)

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- **1** a distinguished element $\alpha \in D$.

 $(\langle \mathbf{Q}, \mathbf{S} \rangle)$ must be distinct from $\langle \mathbf{P}, \mathbf{R} \rangle$.)

The operator transforms a model M (of signature $\langle P, R \rangle$) to the model $[A, G, H, \alpha]M$ (also of signature $\langle P, R \rangle$) by the method illustrated in the previous example.

General Dynamic Operators: Axiomatisation

It is possible to define a translation from φ to $\varphi^{[\mathbf{A},\mathbf{G},\mathbf{H},\mathbf{a}]}$ such that

$$M, \mathbf{u} \models \varphi^{[\mathbf{A}, \mathbf{G}, H, \mathbf{a}]}$$
 iff $[\mathbf{A}, \mathbf{G}, H, \mathbf{a}]M, \langle \mathbf{u}, \mathbf{a} \rangle \models \varphi$

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And so we can extend the standard axioms and rules of PDL with the schema

$$[\mathbf{A},\mathbf{G},\mathbf{H},\mathbf{a}]\varphi\leftrightarrow\varphi^{[\mathbf{A},\mathbf{G},\mathbf{H},\mathbf{a}]}$$

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The proof is automata-theoretic, making use of the correspondence between PDL programs and automata, and the relative ease of product-like constructions with automata.

Update = merge + integration

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- First compute the effect of transparent changes (those know to all) and merge.
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Different rules for integration express different theories of interaction. (Thanks to Johan van Benthem for this pithy slogan.)

Some directions

- an algebraic approach: how to understand this product in the category of PDL-transformations
- a better axiomatisation: the one we give is somewhat indirect, involving automata theory. Is there a more direct translation?
- higher-order / lower-order interaction: weakness of will, permissible law changes, changing what is possible to do.